CIL

EMU CRITICAL ITEMS LIST

#### 5/30/2002 SUPERSEDES 12/24/1994

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Date: 3/27/2002

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NAME		FAILURE		
P/N	CRIT	MODE &		
QTY	CRIT	CAUSES	FAILURE EFFECT	RATIONALE FOR ACCEPTANCE
		132AFM02A		
PRESSURE	2/2	Drifts low.	END ITEM:	A. Design -
TRANSDUCER			False	-5 Conrac and -7 Gulton:
FEEDWATER SUPPLY,		Pressure increase in the sensor reference cavity due to leakage	indication of	The sensing element is made of an all welded solution hardened Inconel diaphragm
ITEM 132A			low gas	to maximize strength and reduce any shift due to over stressing. All
			reservoir pressure.	linkage/resistive element attaching screws are potted in place to prevent
SV767793-7				shifting. The assembly is vacuum outgassed and temperature cycled until stable. The sensor design minimizes sensor output shifting, increase in friction and
(1)				excessive resistive element wiper wear. The vacuum reference cavity is
			GFE INTERFACE:	hermetically sealed in an all metal/glass, welded/ brazed case.
		through the	Sensor 132B	nermetically scaled in an all metal/glass, werded, stated case.
SV767793-8		case or	provides	B. Test -
()		sensing element. Failure of the potentiometer linkage due to increased friction. Mechanical	redundant	Component Acceptance Test -
			pressure	Conrac: The sensor is subjected to acceptance testing per Conrac procedure
			reading.	ATP451379-64 prior to shipment by the assembly vendor. This testing includes the
			Unable to	following tests to insure the sensor is stable:
			detect when on	The sensor is subjected to random vibration testing (6.1 grms) to insure there
			reserve water.	are no workmanship or material problems that would cause the voltage to shift
				low. The sensor is subjected to calibration testing at high and low temperature (30 to 120 degrees F) to insure there are no defects that thermal
		shock loading	MISSION:	expansion/contraction would uncover. The sensor is calibration checked during
		of the linkage which causes a	Terminate EVA.	acceptance testing to insure sensor is stable and proof pressure tested for one
			Loss of use of	minute at 24 psia to insure pressure stability.
		misalignment	one EMU.	Gulton: The sensor is subjected to acceptance testing per Gulton procedure ATP
		of the		3031-15201 prior to shipment by the assembly vendor. This testing includes the
		resistive		following tests to insure the sensor is stable:
		element	CREW/VEHICLE:	The sensor is subjected to random vibration testing (6.1 grms to insure there
		relative to	None.	are no workmanship or material problems that would cause the voltage to lower.
		the wiper.		The sensor is subjected to calibration testing at low temperature to insure
		Failure of the resistive coil due to an opening on the high voltage	TIME TO EFFECT	there are no defects that thermal expansion/contraction would uncover. The sensor is calibration checked during acceptance testing to insure sensor is
			/ACTIONS: Seconds.	stable and proof pressure tested for one minute at 24 psia to insure pressure
				stability.
		side of the coil.	TIME	PDA Test -
			AVAILABLE:	The sensor is calibration checked at 0 and 16.0 psia as assembled on the PLSS to
			Days.	insure the output voltage is within spec limits per SEMU-60-010, Test 27.
			TIME REQUIRED:	Certification Test -
			Minutes.	Certified for a useful life of 20 years (ref. EMUM1-0084).
			REDUNDANCY	C. Inspection -
			SCREENS:	Inspection - Conrac: The sensor is visually inspected prior to case assembly to
			A-N/A	insure there are no workmanship problems which could cause the output voltage to
			B-N/A C-N/A	shift low. The sensor is calibration checked at various steps in the assembly
				process to insure the sensor output is within specified limits.
				Gulton: The sensor is visually inspected prior to assembly to insure there are
				no workmanship problems which could cause the output voltage to shift low. The
				sensor is calibration checked at various steps in the assembly process to insure
				the sensor output is within specified limits. The sensor is pressure cycled for at least 350 cycles during assembly to insure the sensor is stabilized. The
				sensor is temperature cycled between -65 degrees F and +200 degrees F to insure
				it is stable.

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			Date: 3/2//2002
	MODE &	FAILURE EFFECT	RATIONALE FOR ACCEPTANCE
·	132AFM02A		
			D. Failure History - The following RDR's were issued for Item 132 due to output voltage shifting low. All failures were due to leakage of ambient gas into the reference cavity due to cracking of the glass connector. The connectors have been changed to individual glass bead connectors which are more reliable:
			A. EMU-132-C001, 02/19/78 B. EMU-132-C002, 03/09/79 C. EMU-132-C003, 01/29/80 D. EMU-132-C004, 01/29/80 E. EMU-132-D001, 06/11/79 F. H-EMU-132-S001, 06/06/80 G. J-EMU-132-C001, 10/08/80
			E. Ground Turnaround - Tested for non-EET processing per FEMU-R-001, Transducer and DCM Gage Calibration Check. FEMU-R-001 Para 8.2 EMU Preflight KSC Checkout for EET processing.
			F. Operational Use - Crew Response - EVA: When CWS data confirms loss of feedwater gas pressure, trouble shoot problem. If failure can be determined to be sensor, continue EVA. Training - Standard EMU training covers this failure mode. Operational Considerations - No constraints for single failure. Flight rules define go/no go criteria releated to EMU suit thermal control. EVA checklist procedures verify hardware integrity and systems operational status prior to EVA. Real Time Data System allows ground monitoring of EMU systems.
			MODE & RIT CAUSES FAILURE EFFECT

# EXTRAVEHICULAR MOBILITY UNIT

## SYSTEMS SAFETY REVIEW PANEL REVIEW

## FOR THE

## I-132 FEEDWATER SUPPLY PRESSURE SENSOR

CRITICAL ITEM LIST (CIL)

## EMU CONTRACT NO. NAS 9-97150

Prepared by: <u>Approved by:</u> <u>RMB</u> <u>NAME</u>

M. Smylin HS - Reliability

HS - Engineerin low

3/00/02

TISSIM

NASA-MOD

NASAL Crew

Program Manager