

Grumman Corporation

CRITICAL ITEMS LIST

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GRUMMAN

ASSY NOMENCLATURE: MANIPULATOR FOOT RESTRAINT

PREPARED BY: L. HAHN & F. PERAZZO

REPORT NO: RMS 87 R 1

ASSEMBLY PART NO: SED 3040100

REVISION: A

DATE: 17 MAY 1988

FMEA REF	REV	NAME, QTY & DRAWING REF DESIGNATION	CRIT	FAILURE MODE AND CAUSE	FAILURE EFFECT	RATIONALE FOR ACCEPTANCE
F4		Hand Hold Assembly (HHA) (containing retainers for tool boards) QTY (1) Dwg C95-118	2/2	F4 - Tool board retainer leaf spring jammed or lock failed in closed position	<p>END ITEM Tool board guide will not release tool board; possible interference between tool board and grapple fixture/RMS end effector interface when moving the vertical stanchion to the stowed position</p> <p>GFE INTERFACE None, since MFR will be jettisoned</p> <p>MISSION Loss of MFR; unable to accomplish subsequent mission objectives</p> <p>CREW/VEHICLE None</p>	<p>A. Design In addition to considering the launch loads discussed under cases A1 and B1, the MFR has been designed to accommodate the following conditions in the deployed configurations: - Astronaut handling loads of one hundred pounds in any direction. - Inertial response loads of MFR to RMS runaway accelerations (2.6 ft/sec/sec linear accel, y, or z axis and 0.5 rad/sec/sec float accel about x axis) - RMS constrained motion load of 300 pounds ultimate, any point, any direction. - 140 pound couple by each foot to footplate assembly - 343 pound load applied to any tether/reel assembly. - The design minimizes orbital EVA thermal stresses by utilizing aluminum as the one basic structural material, coated with a low absorption thermal control coating per Grumman spec CSS-MFR-PS-001 Using the above load spectrum design safety margin of 1.14 for deformation and 1.40 for failure have been achieved. All springs are corrosion resistant and will be cycled a small fraction of nominal cyclic life in the 20 mission life of the MFR. Fatigue life based upon random response loads with appropriate stress concentration factors has been established using a scatter factor of 4.0 (e.g., B0 mission fatigue life based upon S-N curves) All materials are per table 1 and 2 of MSFC SPEC 522A, to reduce stress corrosion and are certified for traceability/quality.</p>

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GRUMMAN

ASBY NOMENCLATURE: MANIPULATOR FOOT RESTRAINT

PREPARED BY: L. HAHN & F. PERAZZO

REPORT NO: AMS 87 A A

ASSEMBLY PART NO: 84D 2010180

REVISION: A B

DATE: 8 JULY 1988

FMEA REF REV	NAME, QTY & DRAWING REF DESIGNATION	CRIT	FAILURE MODE AND CAUSE	FAILURE EFFECT	RATIONALE FOR ACCEPTANCE
F4	Hand Held Assembly (HHA) (containing retainers for tool boards) QTY (1) Dwg C95-118	2/2	F4 - Tool board retainer leaf spring jammed or lock failed in closed position	<p>END ITEM Tool board guide will not release tool board; possible interference between tool board and grapple fixture/RMS and effector interface when moving the vertical stanchion to the stowed position</p> <p>GFE INTERFACE None, since MFR will be jettisoned</p> <p>MISSION Loss of MFR; unable to accomplish subsequent mission objectives</p> <p>CREW/VEHICLE None</p>	<p>B. TEST HISTORY 1. Acceptance test per procedure 388-94.01 at Grumman (7/7/83) before and after all tests. ATP includes functional of all operating mechanisms and a general visual inspection. 2. Stiffness test per procedure 388-101.01 at Grumman (7/7/83). Demonstrated stanchion end play less than 5 inch for a five pound load in any direction and deflection less than 3 inches lateral and 2 inches longitudinal for 1 hundred pound loads. 3. Vibration and shock test per procedure 388-98.01 at Grumman (7/7/83). Demonstrated ability to withstand design levels without structural failure with no significant resonance. Several screws required the application of lockite. 4. APC/MFR ultimate load tests per STS-83-8944 at Rockwell (8/83). Loads applied in 14 steps, each comprising 80% of final load; no yield was observed at the ultimate load of 14,400 lbs. 5. Thermal vacuum test at JSC (7/29/84). MFR was operated at ambient temperature, plus 224 F and -127 F (average lowest achievable chamber temp) at an average vacuum of .00006 torr. 6. Center of gravity test at JSC (12/2/84). 7. Moment of inertia swing test at JSC (9/4/85).</p> <p>C. INSPECTION 1. NAVPRO inspects of production end items at completion of final assembly. 2. Anodic hard coated aluminum parts inspected for compliance to MIL-A-8625 C by DCAS. Certificate of compliance on file at Grumman Bethpage. 3. Thermal Control Coating process is controlled by inspections (post prime, cure, post coating and cure), and sample testing for coating thickness, coating adhesion, and emittance/solar absorption.</p> <p>D. FAILURE HISTORY None (per FMACA database). The MFR has been successfully utilized on live missions, STS 81, 81, 51A, 51L, and 61C.</p> <p>E. TURNAROUND Inspection per S28/PIA 05801/PIA 10 DEC 1987 includes a functional test of all MFR operating functions, and a general visual inspection.</p> <p>F. OPERATIONAL USE 1. Operational Effect of Failure: MFR could not be restored; it possibly could not be used on a second EVA if it had to be jettisoned. 2. Crew Action: Crew could remove hardware from the tool board if possible. Otherwise, MFR would have to be jettisoned. 3. Crew Training: none. 4. Mission Training: none. 5. In Flight Checkoff: Operation of tool board release will be</p>

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